

Estimation of error propagation and prediction intervals in Multivariate Curve Resolution Alternating Least Squares using resampling methods

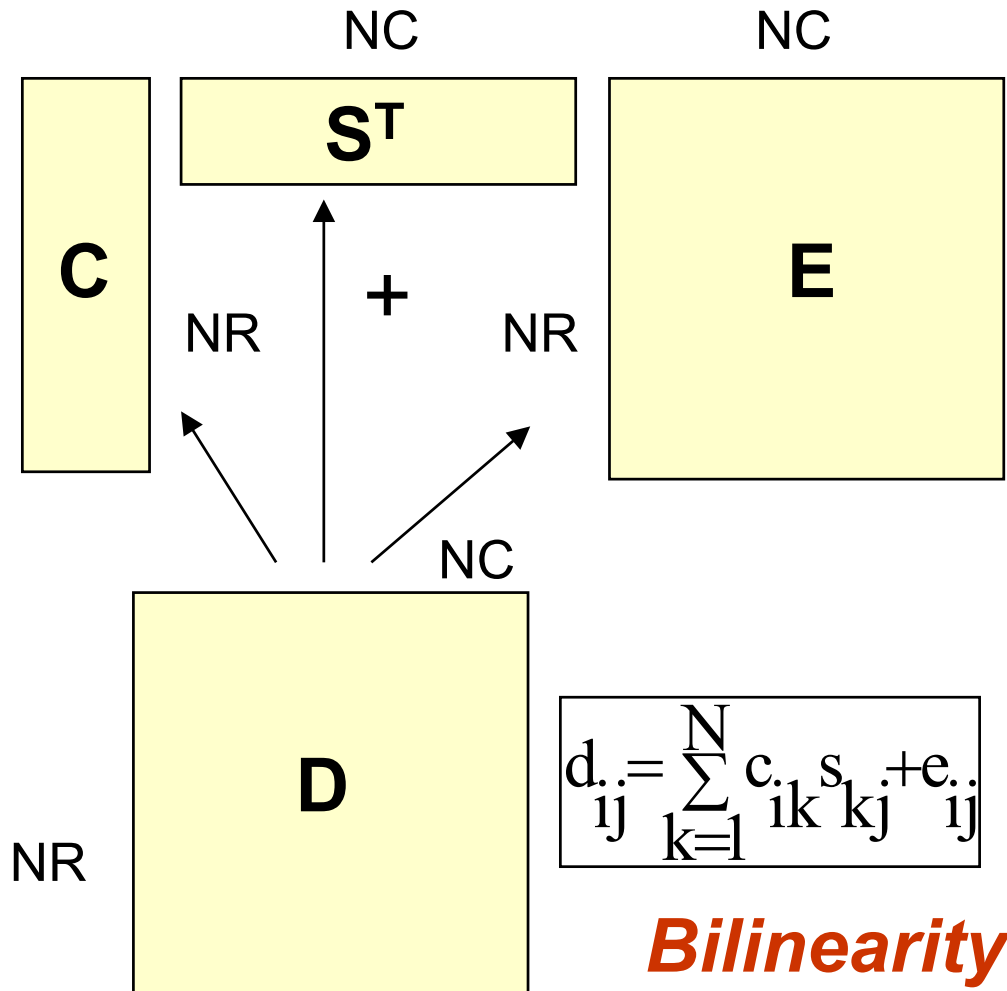
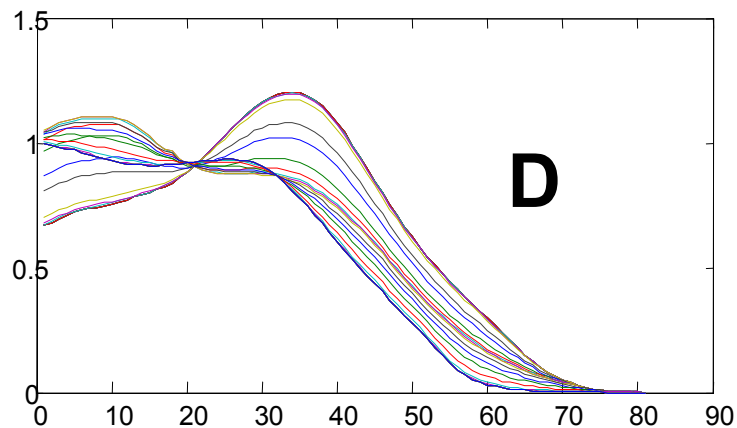
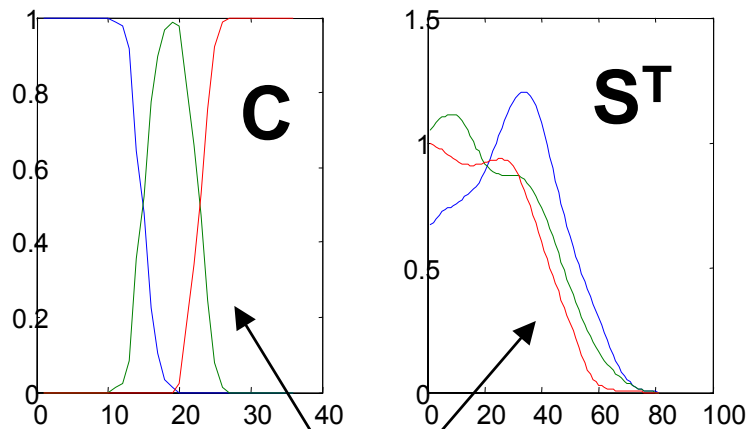
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Outline:

- **Introduction**
- Rotational ambiguities and feasible bands
- Error propagation and resampling methods
- Results
- Conclusions

Multivariate (Soft) Self Modeling Curve Resolution



$$d_{ij} = \sum_{k=1}^N c_{ik} s_{kj} + e_{ij}$$

Bilinearity!

Multivariate (*Soft*) *Self Modeling* Curve Resolution

- **Multivariate Curve Resolution (MCR)** methods have been shown to be powerful self-soft-modeling tools able to investigate complex chemical systems with a minimum number of assumptions.
- **Alternating Least Squares (ALS)** has become a popular method for Multivariate Curve Resolution (MCR) due to its flexibility in constraint implementation during the optimization of resolved profiles.

Multivariate (*Soft*) *Self Modeling* *Curve Resolution*

- **What are the reliability of MCR-ALS estimations?**
 - Do the MCR-ALS solutions have rotational and scale freedom?
 - Are they unique solutions or exist instead a band of feasible solutions?
 - How errors and noise are propagated from experimental data to ALS estimations?

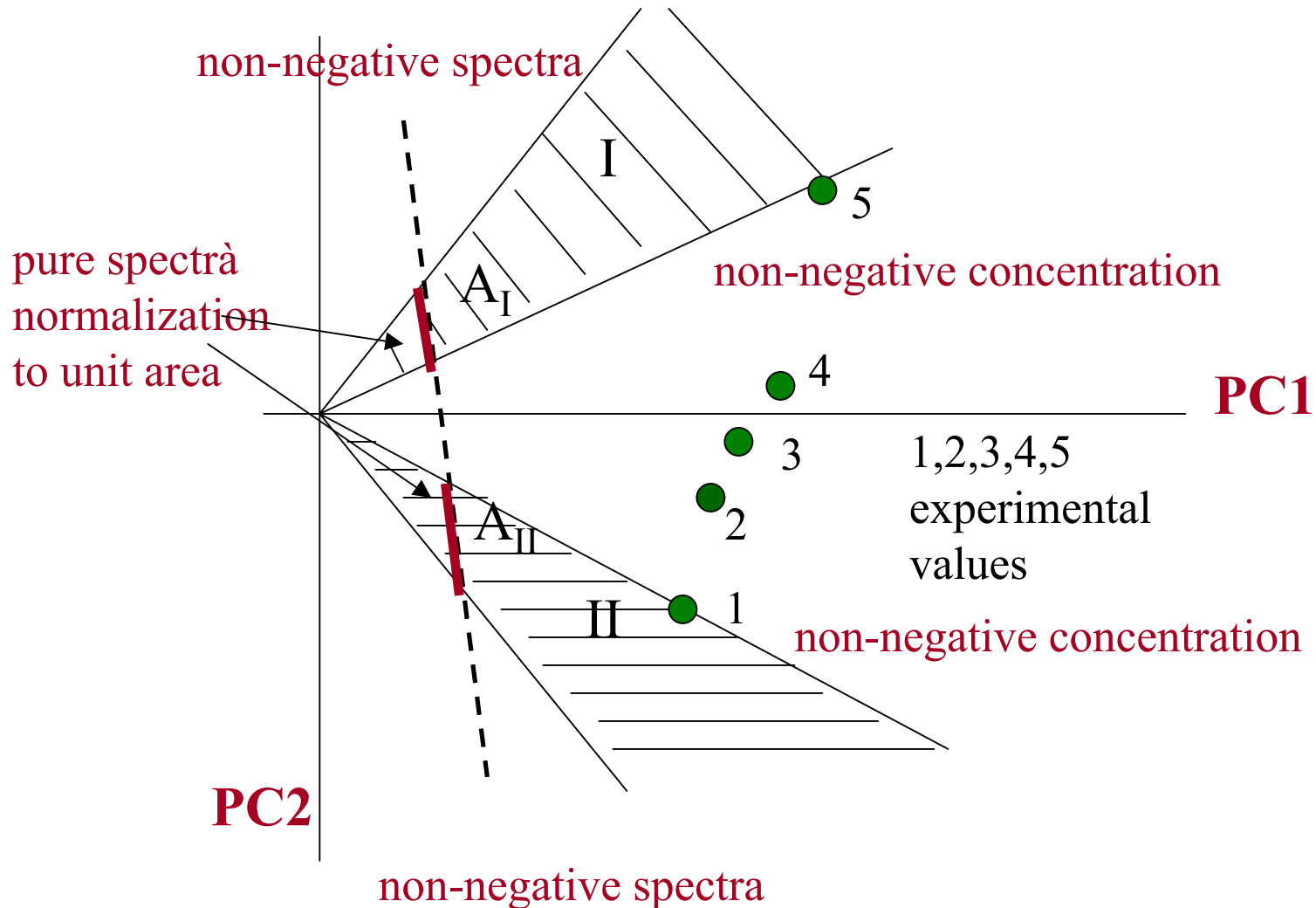
Goals of this study

- Find the **reliability** of ALS resolved profiles in multivariate curve resolution.
- Estimate **prediction error intervals** for ALS profiles
- Estimate **prediction error intervals** for parameters calculated from MCR-ALS resolved profiles
- Investigate the **interaction** between **propagation of errors** and **rotational ambiguities** (noise effects on rotational ambiguities and constraints).

Outline:

- Introduction
- **Rotational ambiguities and calculation of feasible bands**
- Error propagation and resampling methods
- Results
- Conclusions

Lawton and Sylvestre feasible bands



Rotational Ambiguities

Factor Analysis (PCA) Data Matrix Decomposition

$$\mathbf{D} = \mathbf{U} \mathbf{V}^T + \mathbf{E}$$

'True' Data Matrix Decomposition

$$\mathbf{D} = \mathbf{C} \mathbf{S}^T + \mathbf{E}$$

$$\mathbf{D} = \mathbf{U} \mathbf{T} \mathbf{T}^{-1} \mathbf{V}^T + \mathbf{E} = \mathbf{C} \mathbf{S}^T + \mathbf{E}$$

$$\mathbf{C} = \mathbf{U} \mathbf{T}; \quad \mathbf{S}^T = \mathbf{T}^{-1} \mathbf{V}^T$$

How to find the rotation matrix \mathbf{T} ?

Matrix decomposition is not unique!

$\mathbf{T}(\mathbf{N}, \mathbf{N})$ is any non-singular matrix

There is rotational freedom for \mathbf{T}

Rotational Ambiguities

Because of rotational ambiguities instead of unique solutions, a set of *feasible solutions* are obtained

Feasible solutions are different solutions that fit equally well the data under a set of constraints

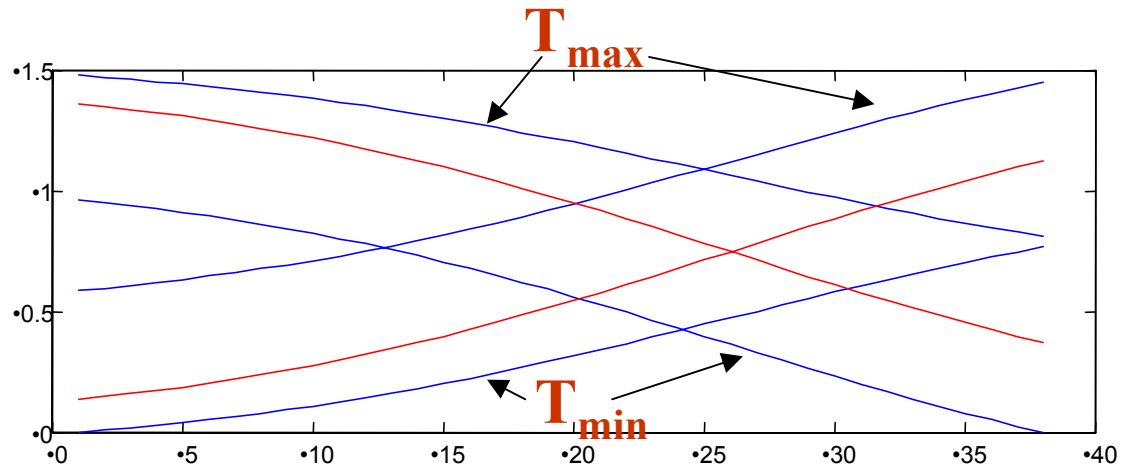
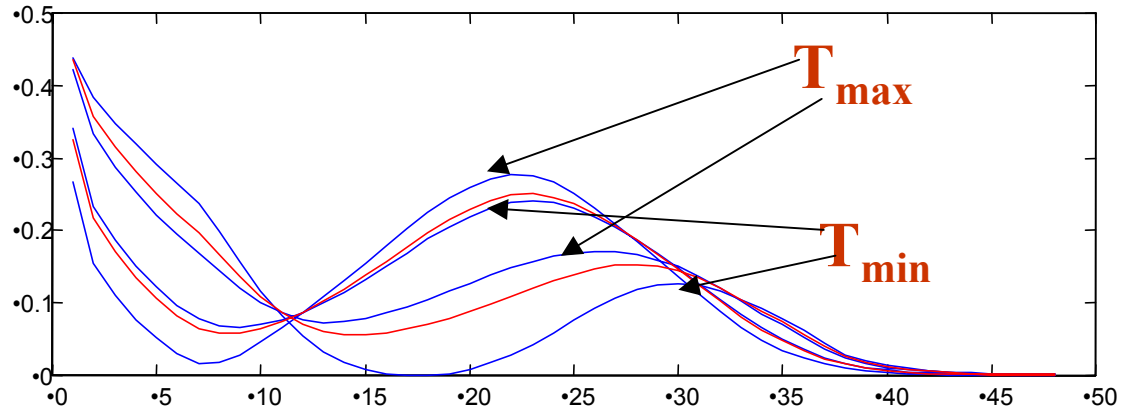
For a particular system under a set of constraints, feasible solutions are defined from a set of possible **T** values.

Rotational Ambiguities

- **T** values define the *band of feasible solutions or feasible bands*
 - How to define the *boundaries* of these feasible bands?
 - How to *represent graphically* these boundaries?

Is it possible to define band boundaries (T_{\max} and T_{\min})?

*How
to
calculate
 T_{\max}
and
 T_{\min} ?*



How to define and find the band boundaries?

- What are the **T** values giving the *maximum/outer and minimum/inner boundaries* of the feasible bands under a set of constraints?

$$\begin{aligned} \mathbf{D}^* &= \mathbf{C}_{\text{inic}} \mathbf{S}_{\text{inic}}^T = \\ &= \mathbf{C}_{\text{inic}} \mathbf{T}_{\text{min}} \mathbf{T}_{\text{min}}^{-1} \mathbf{S}_{\text{inic}}^T = \mathbf{C}_{\text{min}} \mathbf{S}_{\text{min}}^T = \\ &= \mathbf{C}_{\text{inic}} \mathbf{T}_{\text{max}} \mathbf{T}_{\text{max}}^{-1} \mathbf{S}_{\text{inic}}^T = \mathbf{C}_{\text{max}} \mathbf{S}_{\text{max}}^T \end{aligned}$$

where: $\mathbf{D}(\text{NR}, \text{NC})$, $\mathbf{C}(\text{NR}, \text{N})$, $\mathbf{S}^T(\text{N}, \text{NC})$, $\mathbf{T}(\text{N}, \text{N})$

How to define and evaluate \mathbf{T}_{max} and \mathbf{T}_{min} ?

Evaluation of boundaries of feasible bands: Previous studies

- W.H.Lawton and E.A.Sylvestre, *Technometrics*, 1971, 13, 617-633
- O.S.Borgen and B.R.Kowalski, *Anal. Chim. Acta*, 1985, 174, 1-26
- K.Kasaki, S.Kawata, S.Minami, *Appl. Opt.*, 1983 (22), 3599-3603
- R.C.Henry and B.M.Kim (*Chemomet. and Intell. Lab. Syst.*, 1990, 8, 205-216)
- P.D.Wentzell, J-H. Wang, L.F.Loucks and K.M.Miller (*Can.J.Chem.* 76, 1144-1155 (1998))
- P. Gemperline (*Analytical Chemistry*, 1999, 71, 5398-5404)
- R.Tauler (*J.of Chemometrics* 2001, 15, 627-46)
- M.Legger and P.D.Wentzell, *Chemomet and Intell. Lab. Syst.*, 2002, 171-188

Definition of band boundaries

The whole measured signal is:

$$\mathbf{D} = \sum \mathbf{D}_i = \sum \mathbf{c}_i \mathbf{s}_i^T$$

The contribution of each species to the whole signal is:

$$\mathbf{D}_i = \mathbf{c}_i \mathbf{s}_i^T$$

Solving the Optimization Problem:

max/outer boundary: Find \mathbf{T}_{\max} that makes $\mathbf{c}_i \mathbf{s}_i^T$ maximum

min/inner boundary: Find \mathbf{T}_{\min} that makes $\mathbf{c}_i \mathbf{s}_i^T$ minimum

Constrained Non-Linear Optimization Problem (NCP)

Find \mathbf{T} which makes:

$$\begin{array}{ll} \min/\max f(\mathbf{T}) & \text{subject to } \mathbf{g}_e(\mathbf{T}) = 0 \\ \mathbf{T} & \text{and to } \mathbf{g}_i(\mathbf{T}) \leq 0 \end{array}$$

where \mathbf{T} is the matrix of variables, $f(\mathbf{T})$ is a non-linear scalar function of \mathbf{T} and $\mathbf{g}(\mathbf{T})$ is the vector of constraints (non-linear function of \mathbf{T})

Matlab Optimizarion Toolbox *fmincon* function

1) What are the variables of the problem?

T (rotation matrix),

$$\mathbf{D} = \mathbf{C} \mathbf{T} \mathbf{T}^{-1} \mathbf{S}^T$$

2) What is the objective function $f(\mathbf{T})$ to be optimized?

For each species $i = 1, \dots, ns$

$$f_i(\mathbf{T}) = \frac{\|c_i s_i\|}{\|\mathbf{C} \mathbf{S}^T\|} \quad \text{or} \quad f_i(\mathbf{T}) = \frac{\sum_j c_{ij} s_{ij}}{\sum_{i,j} c_{ij} s_{ij}}$$

This gives the relative signal contribution of species i respect the global measured signal !

$f(\mathbf{T})$ is scalar value between 0 and 1!

3) What are the constraints $g(T)$?

The following constraints may be considered:

normalization/closure

$g_{\text{norm}}/g_{\text{clos}}$

non-negativity

$g_{\text{cneg}}/g_{\text{sneg}}$

known values/selectivity

$g_{\text{known}}/g_{\text{sel}}$

unimodality

g_{unim}

trilinearity (three-way data)

g_{tril}

Are they equality or inequality constraints?

4) What are the initial estimates of C , S^T ?

- Initial estimates of C and S^T are obtained by MCR-ALS
- Initial estimates are feasible solutions fulfilling the constraints of the system (*non-negativity, unimodality, closure, selectivity, local rank, ...*)

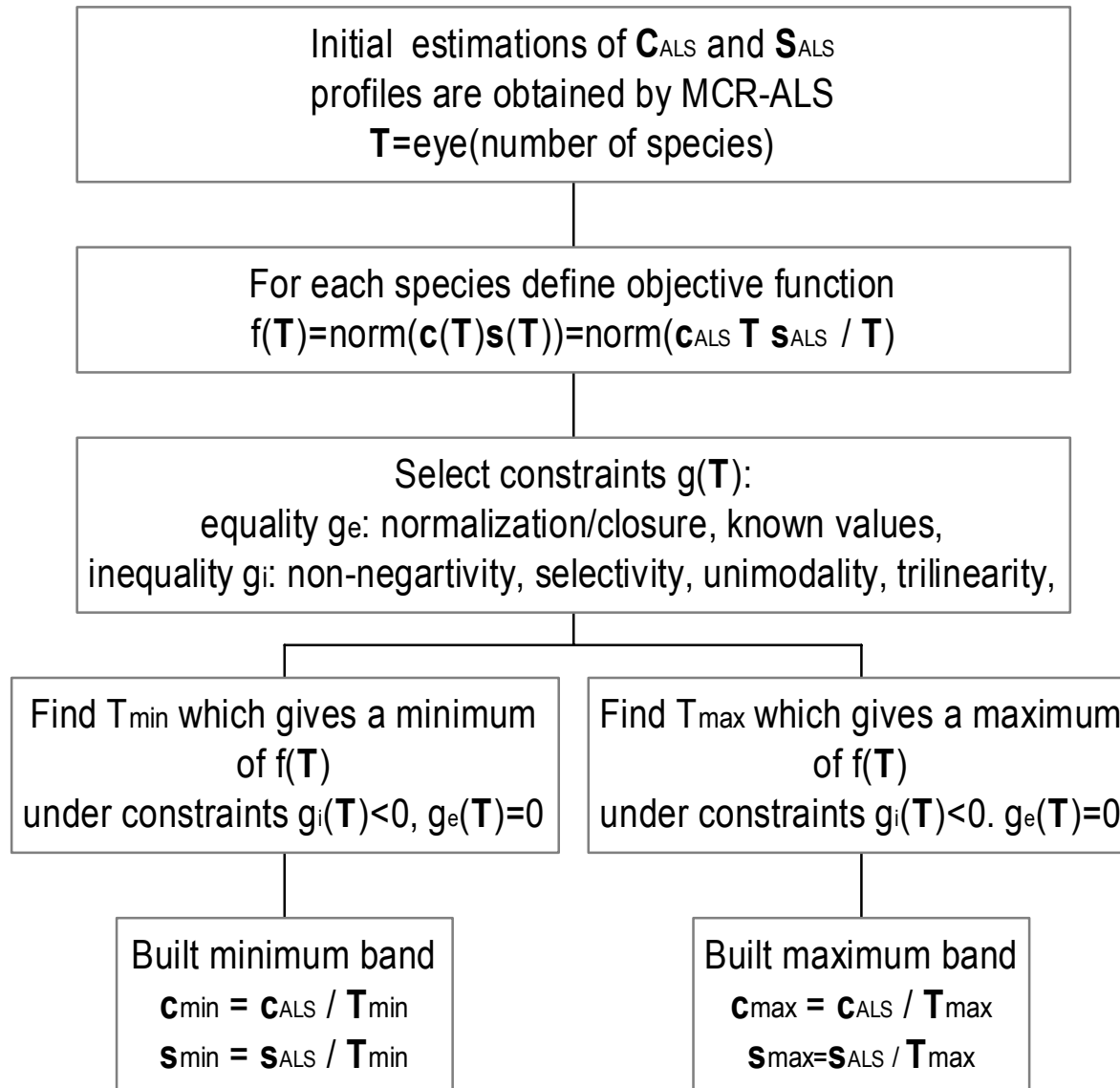
5) What are the initial values of T ?

- NCP depends on initial estimates of T ! (local minima, convergence, speed ...)

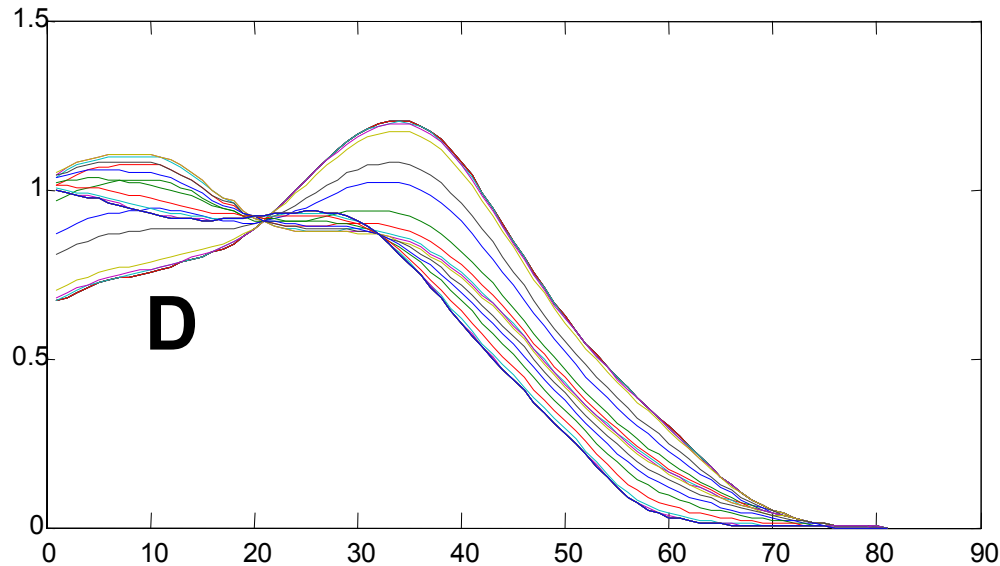
$$\mathbf{T}_{ini} = \mathbf{eye}(N) = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 1 \end{pmatrix}$$

Optimization algorithm

- R. Tauler (J. of Chemometrics 2001, 15, 627-46)

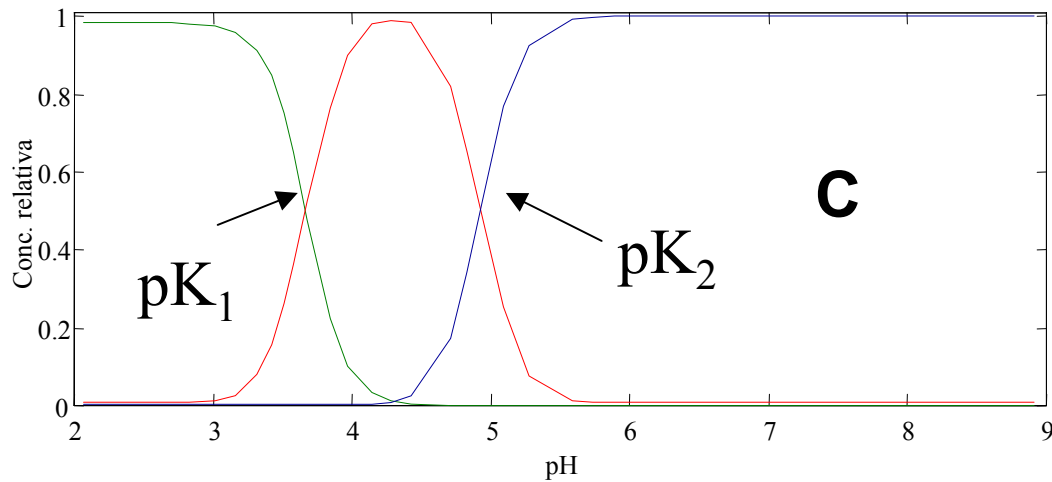


Experimental data system under study

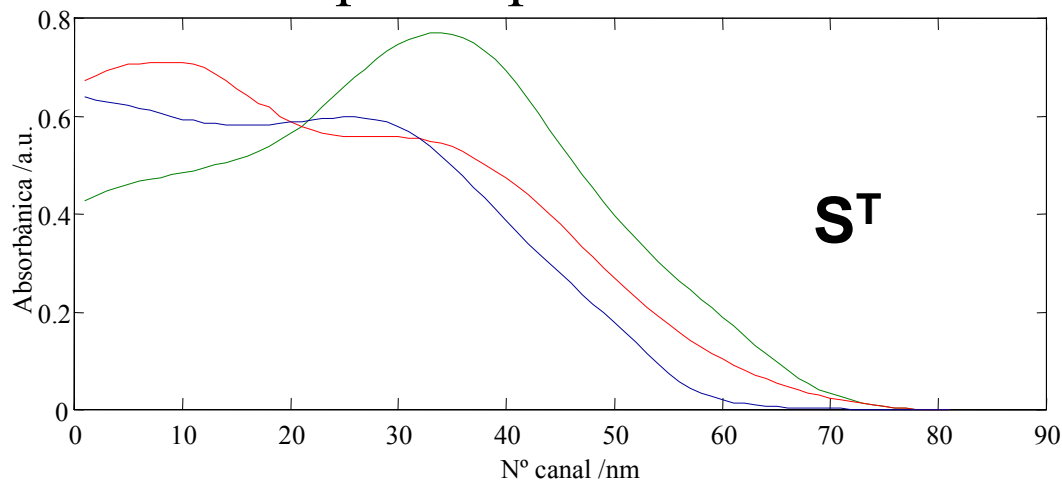


Acid-base spectrophotometric titration of the double stranded heteropolynucleotide polyinosinic-polycytidylic acid. Spectral region between 240-320 nm and pH region between pH 2 and pH 9

concentration profiles



spectra profiles



Application of MCR-ALS to the experimental data matrix **D**

Applied constraints in ALS were:

- non-negative spectra
- non-negative concentrations
- closure in concentrations

Initial estimates were obtained from purest variables

- This system has selectivity! local rank resolution conditions!**
- Initial estimates from pure variable detection methods provide good initial estimates that produce solutions close to the true profiles**

Parameter estimation

Mass-action law is only assumed at the site level and not for the whole polynucleotide molecule

Evaluation of constants
from intersection profiles

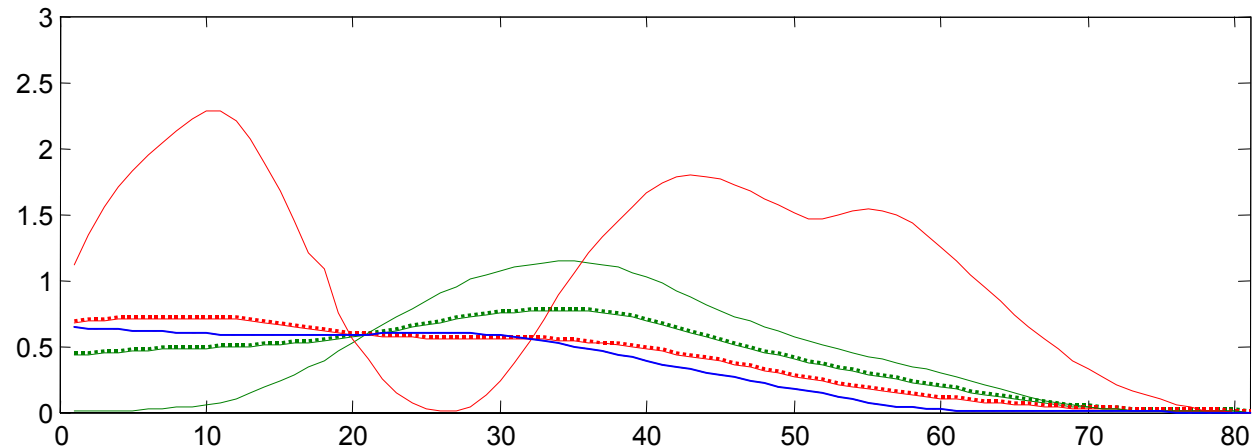
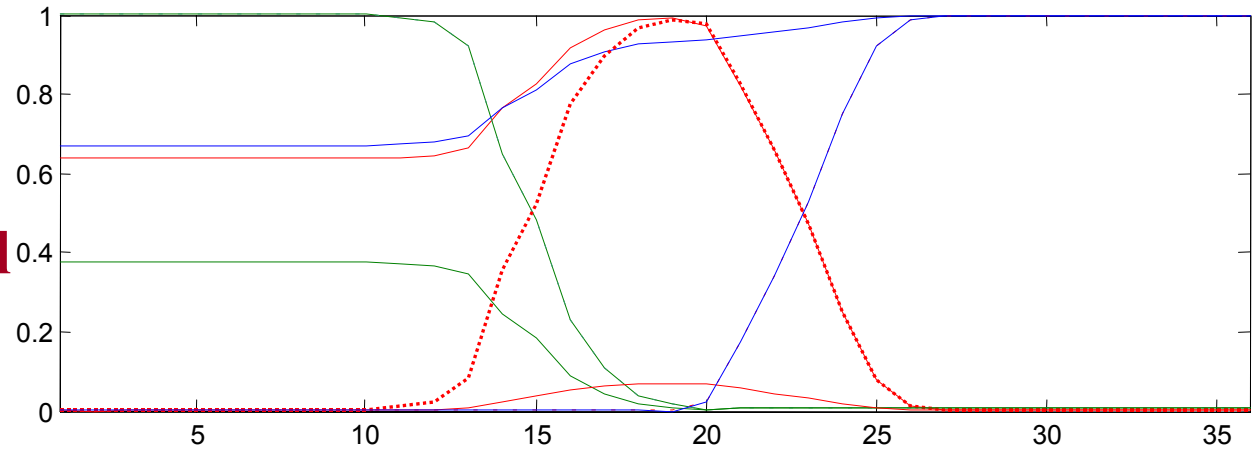
pK_1	3.6660
pK_2	4.9244

Proposed species:



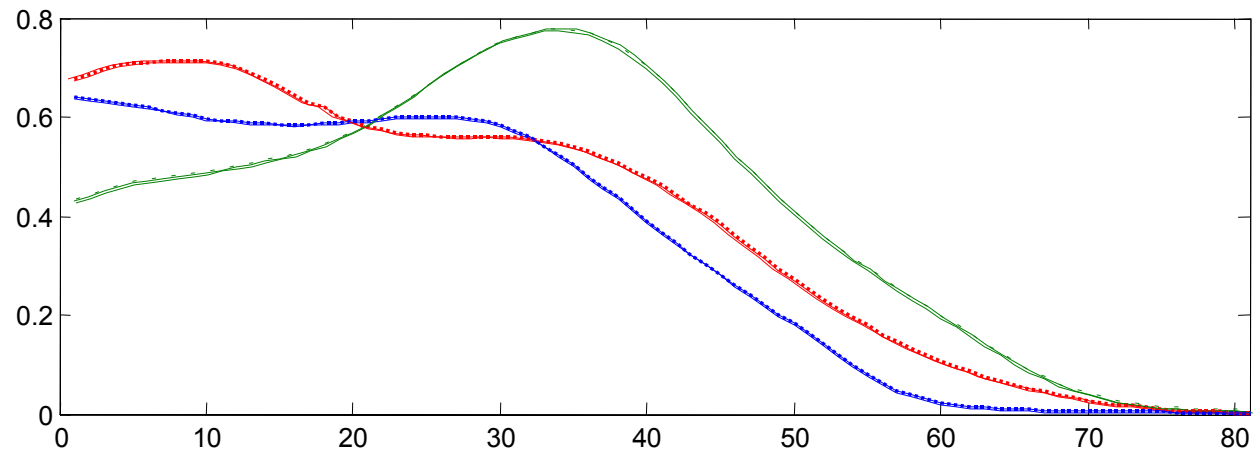
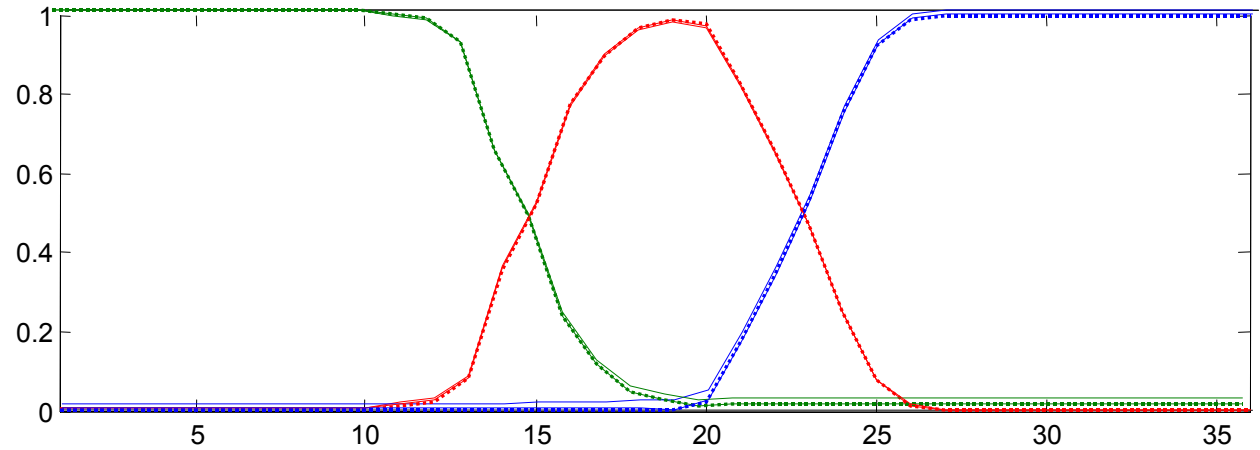
Estimation of band boundaries (max/min contribution of each species) of feasible solutions

Large Rotational ambiguities were present when constraints applied were only closure non-negativity!!!



Estimation of band boundaries (max/min contribution of each species) of feasible solutions

**Rotational
ambiguities
nearly
dissappear
when selectivity
constraint was
applied!!!**



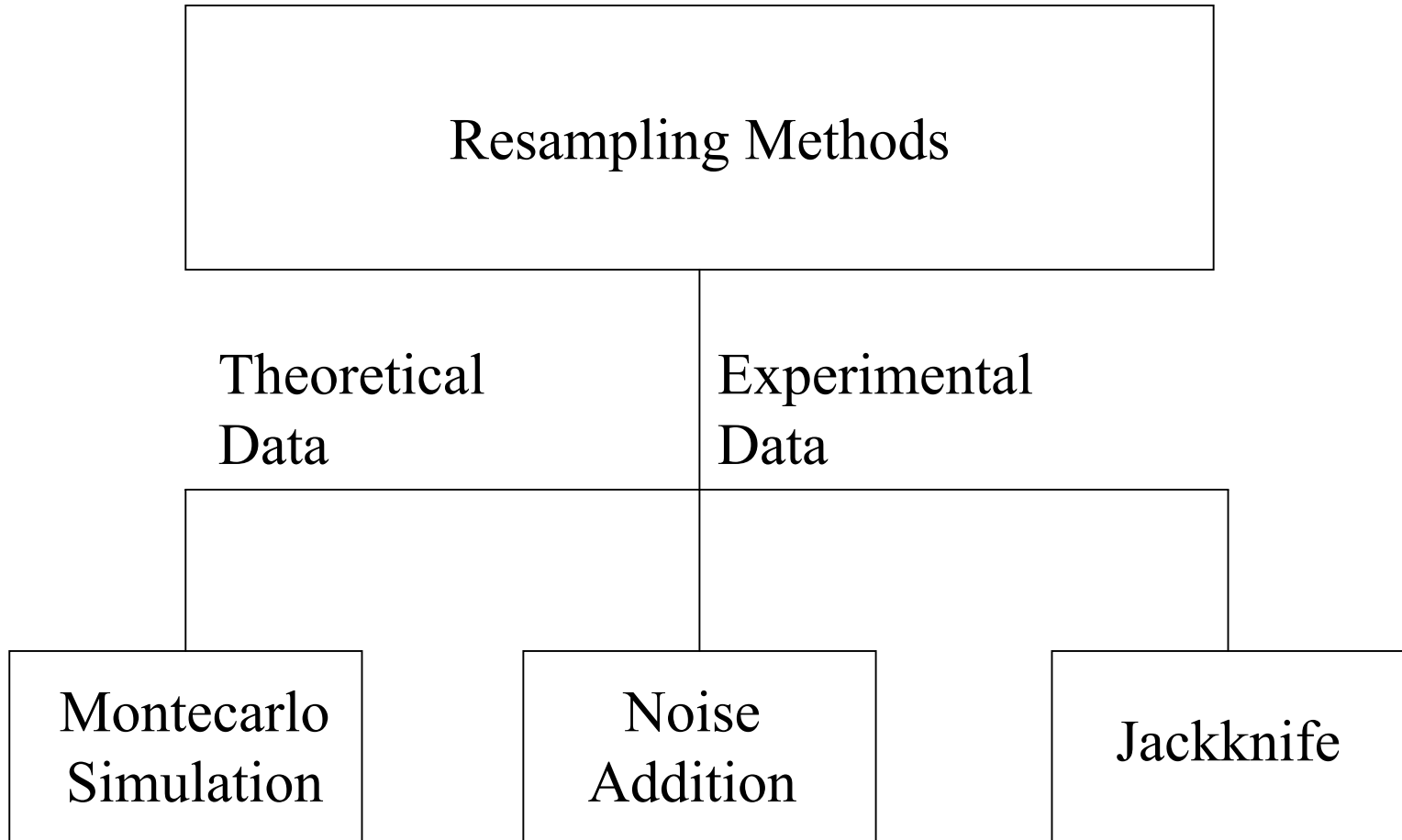
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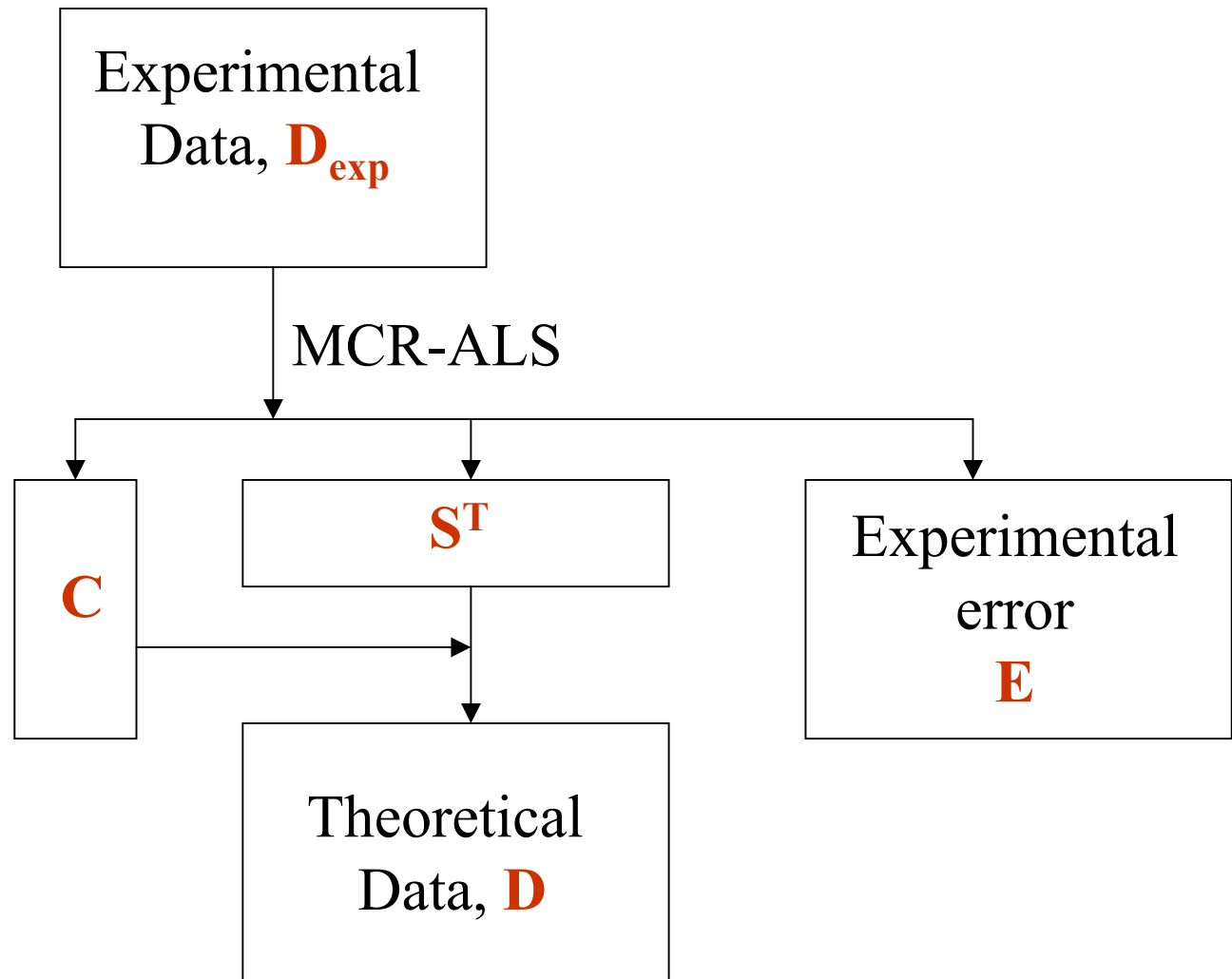
Error propagation and resampling methods

- How **experimental error/noise** in the input data matrices affects MCR-ALS results?
 - For **ALS** calculations there is **no known analytical formula** to calculate error estimations. (i.e. like in linear least-squares regressions)
 - Bootstrap estimations using resampling methods is attempted

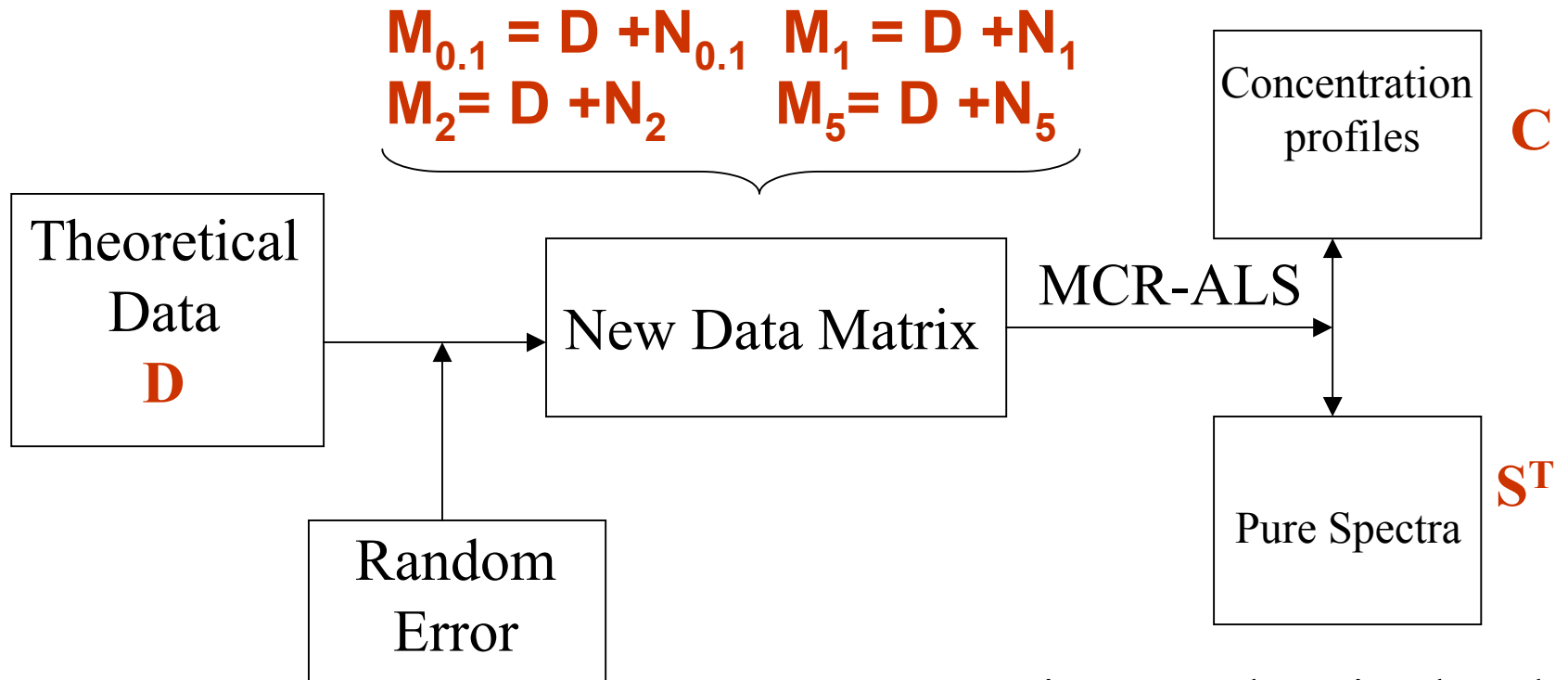
Resampling Methods



Building theoretical data



Montecarlo Simulations



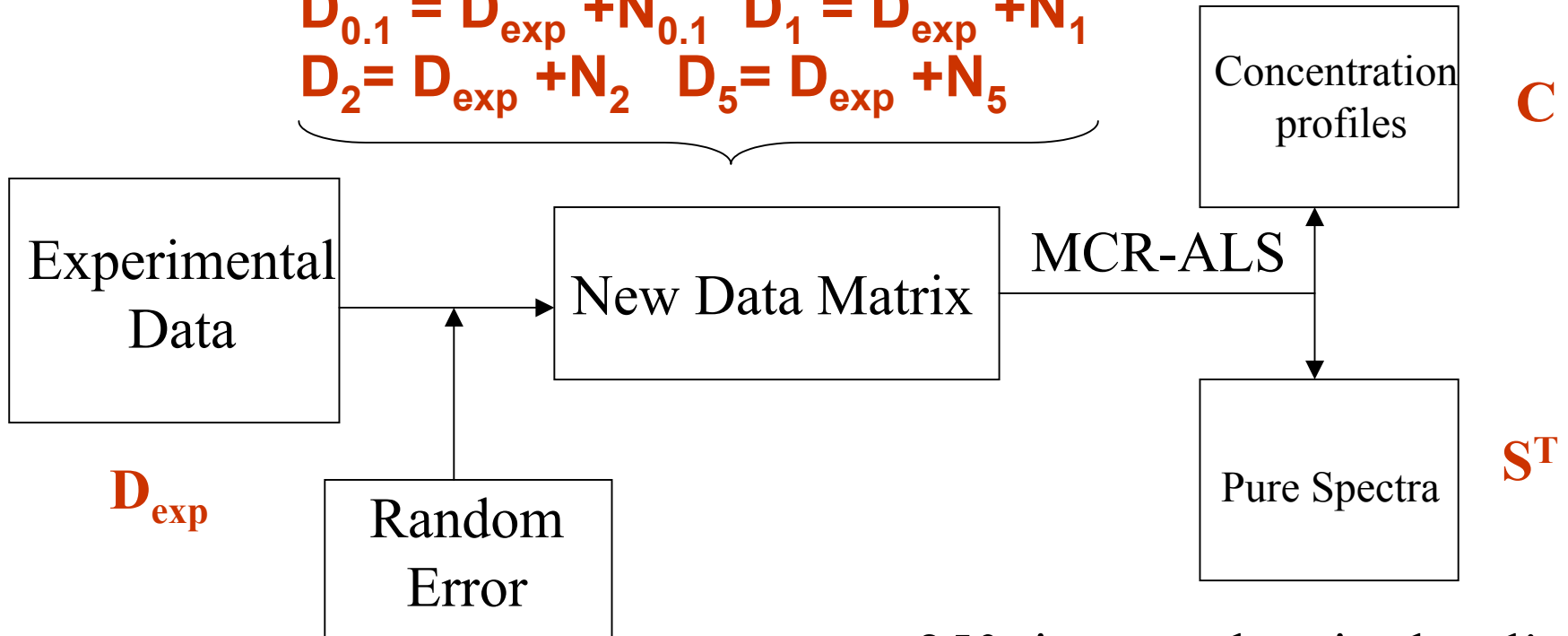
$N_{0.1}, N_1, N_2$ and N_5

250 times each noise level!
1000 simulations!

MATLAB function *randomm* with zero mean and relative sd 0.1%, 1%, 2% and 5% of maximum signal in **D**

Noise Addition Simulations

$$\begin{aligned} D_{0.1} &= D_{\text{exp}} + N_{0.1} & D_1 &= D_{\text{exp}} + N_1 \\ D_2 &= D_{\text{exp}} + N_2 & D_5 &= D_{\text{exp}} + N_5 \end{aligned}$$

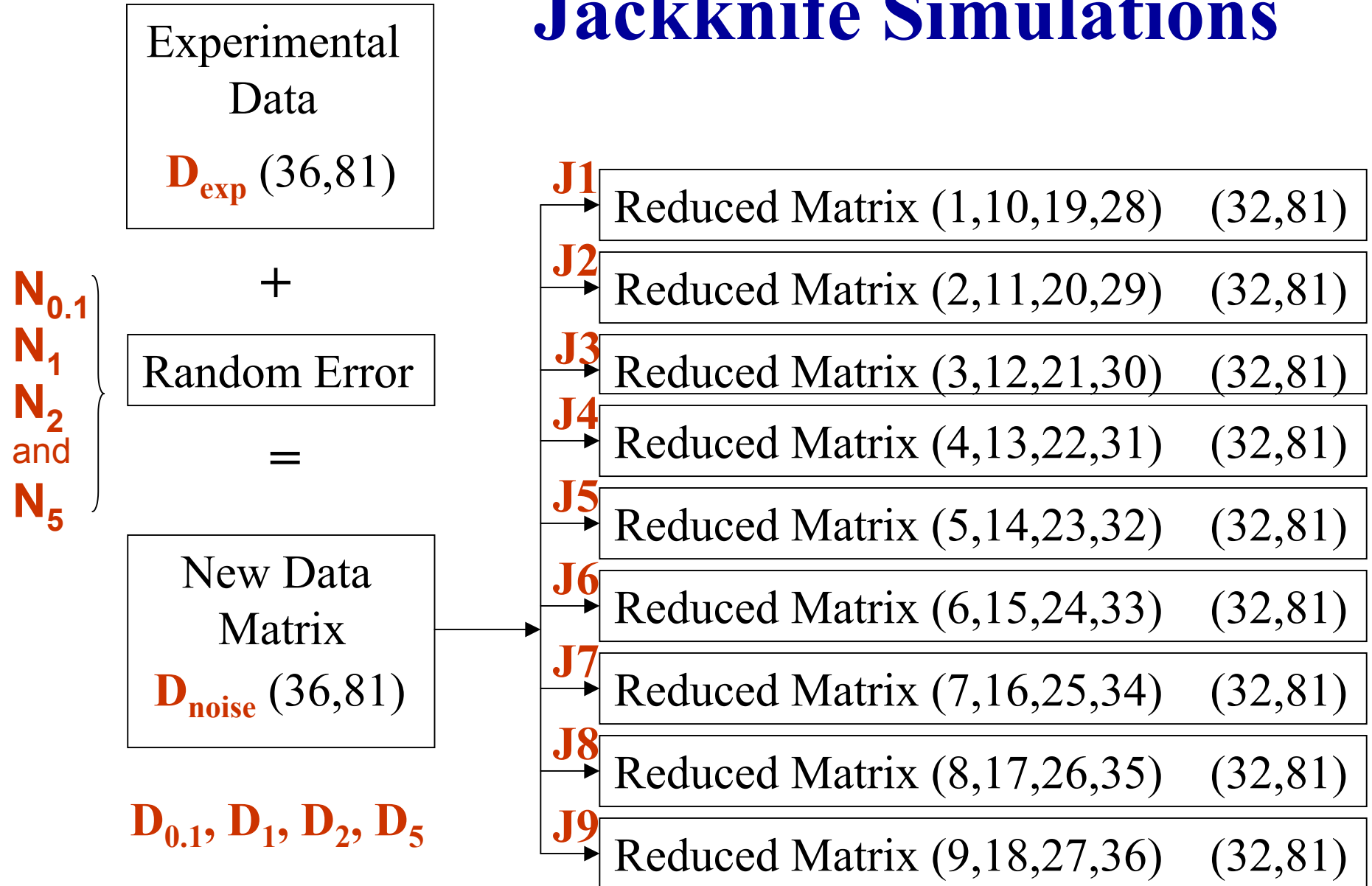


$N_{0.1}, N_1, N_2$ and N_5

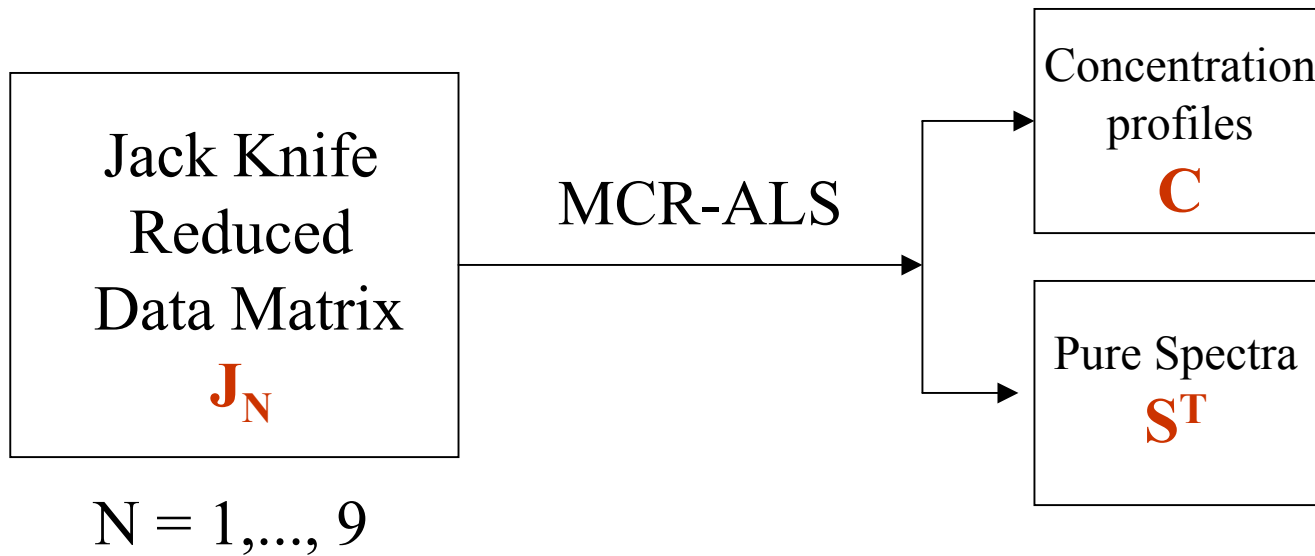
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Jackknife Simulations



Jackknife Simulations

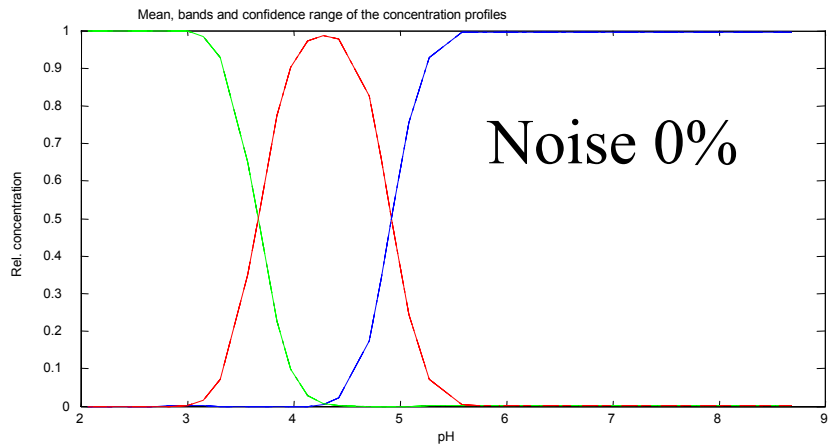


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Presentation of Results

1. Calculation of **species profiles error bands**:
Mean profile, maximum and minimum profiles, standard deviation profiles and confidence range profiles
2. **pKa (parameter) error estimations**
3. Rotational ambiguity effects on error estimates from resampling methods. Calculation of **boundaries of feasible bands from mean species profiles error bands**

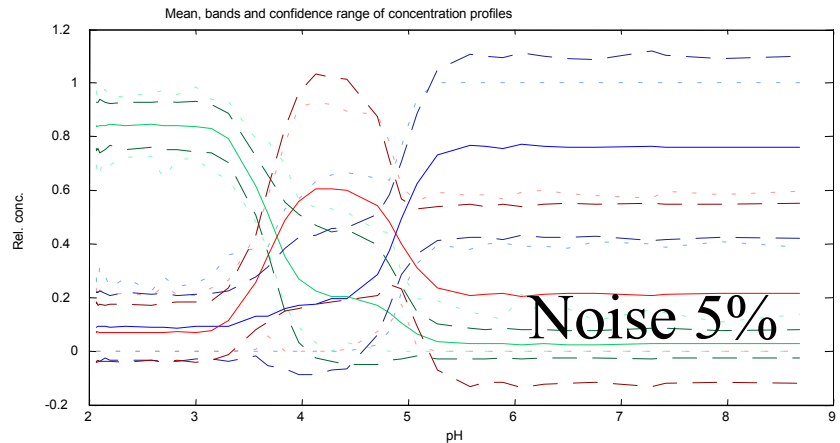
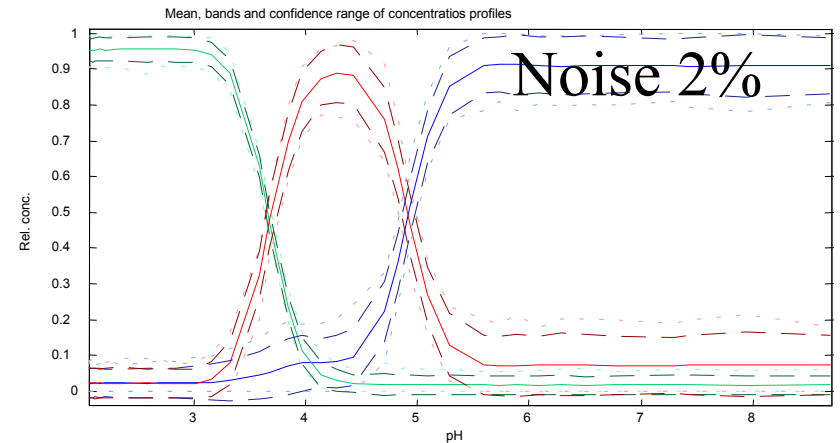
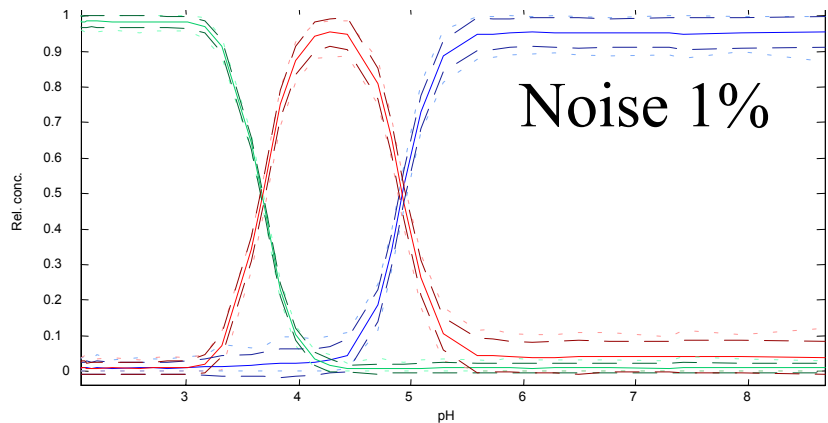
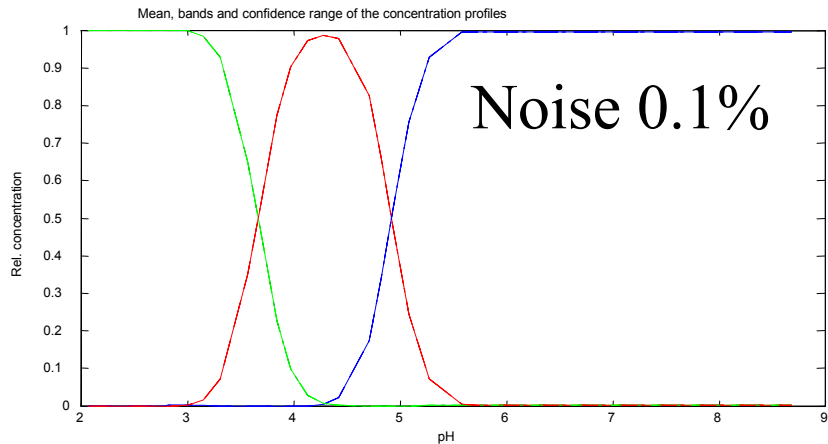


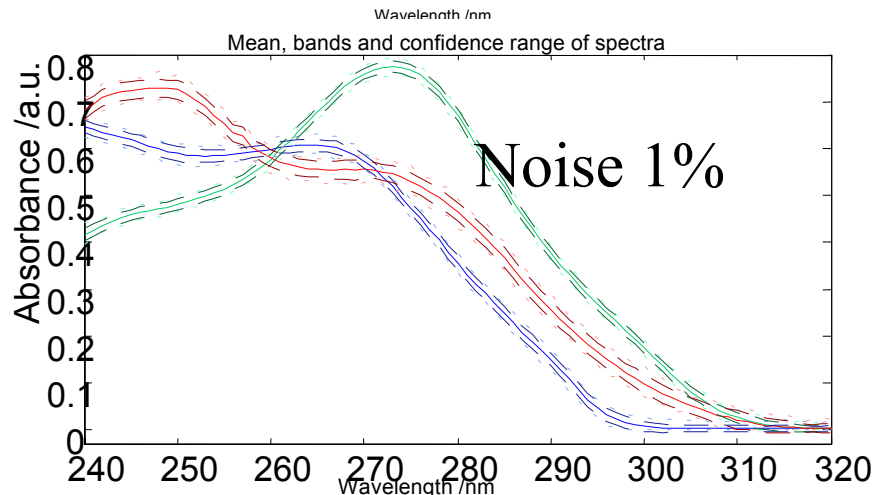
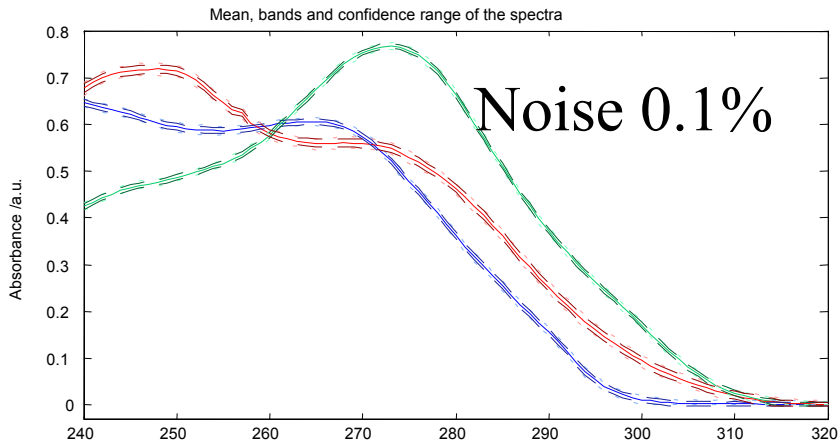
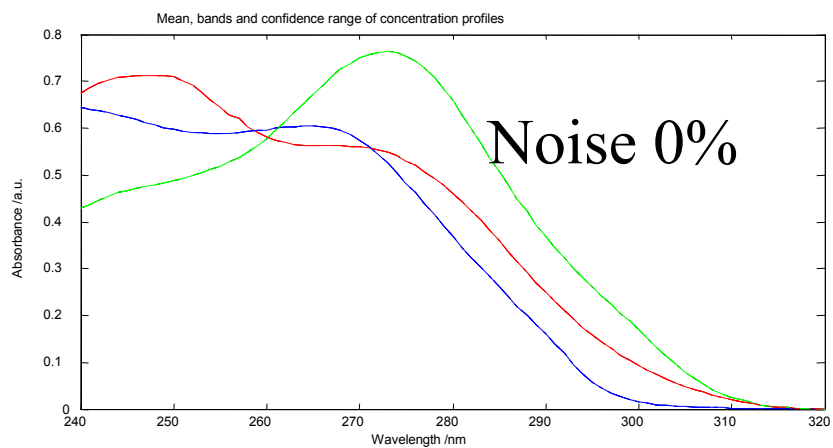
Monte Carlo Simulations

Concentration profiles:

Mean max and min profiles

Confidence range profiles



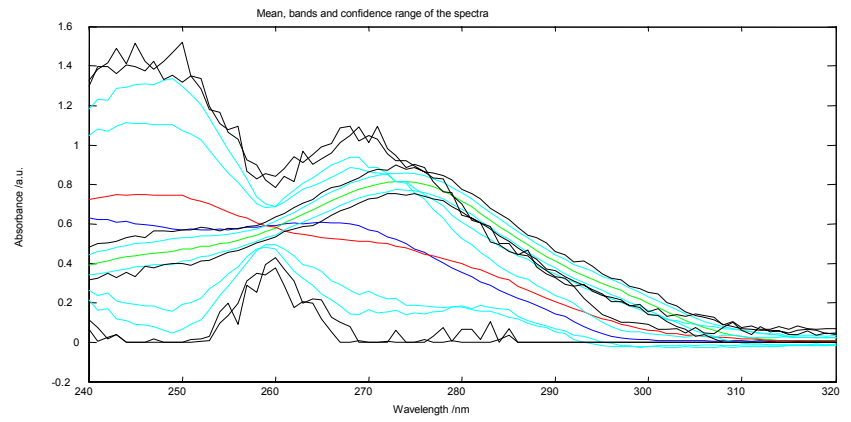
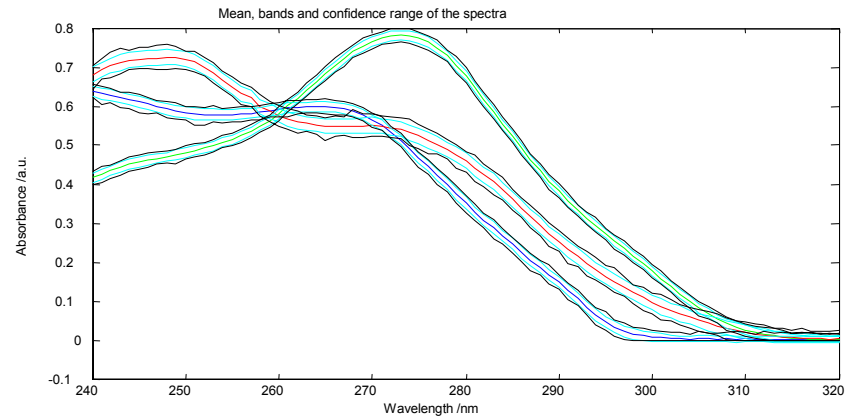


Monte Carlo Simulations

Spectra profiles:

Mean max and min profiles

Confidence range profiles

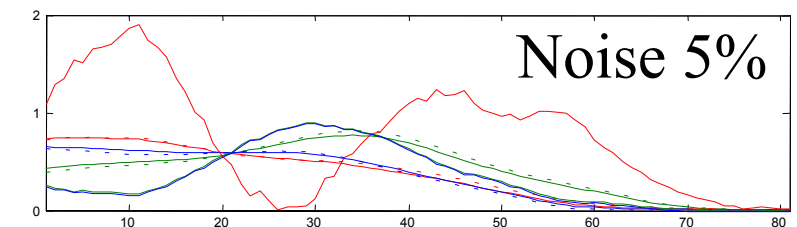
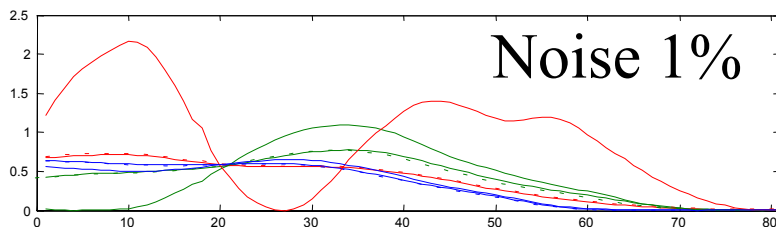
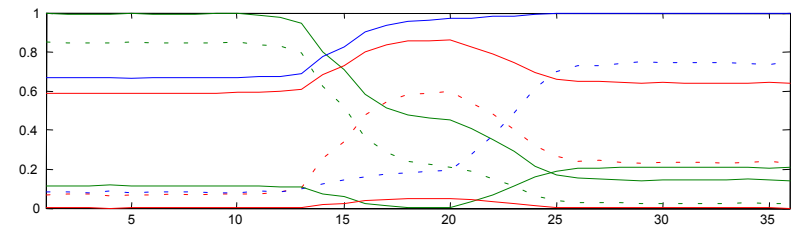
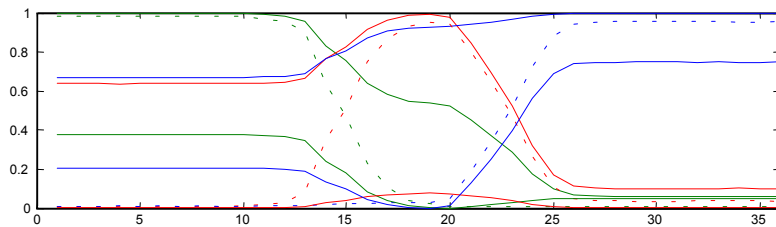
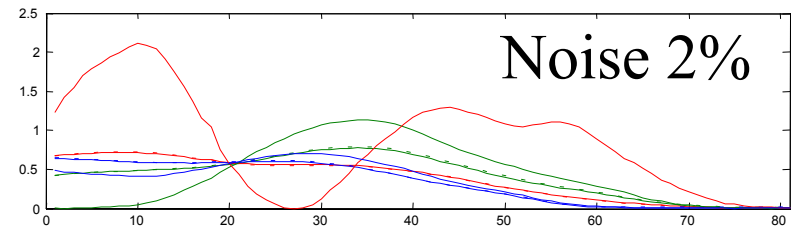
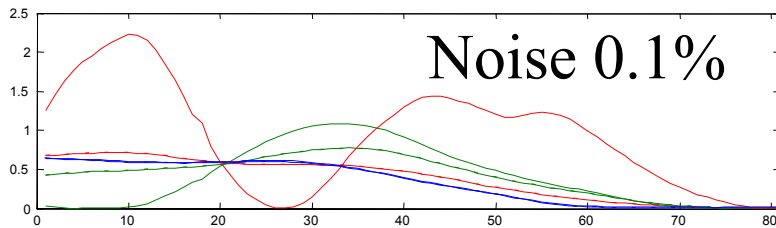
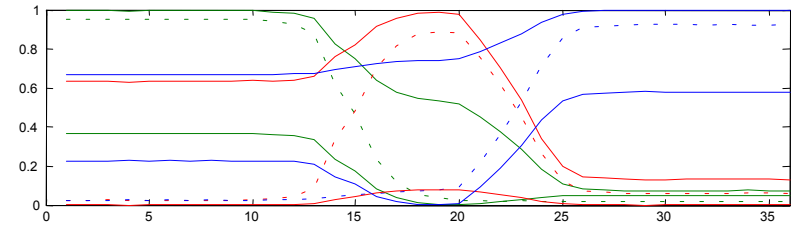
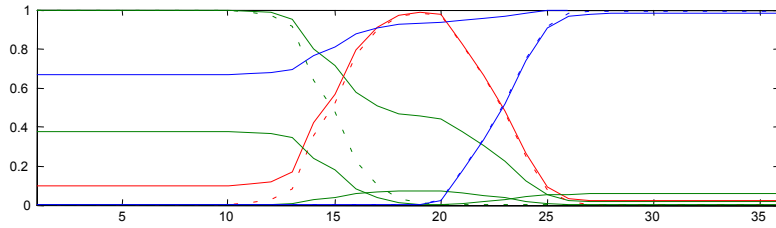


Monte Carlo Simulations

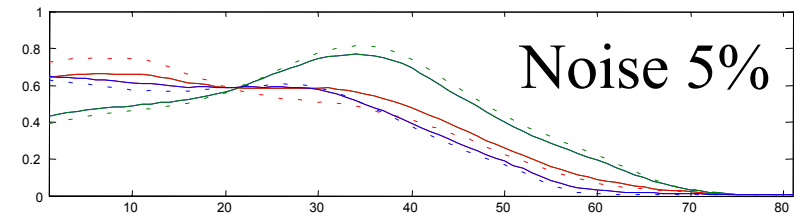
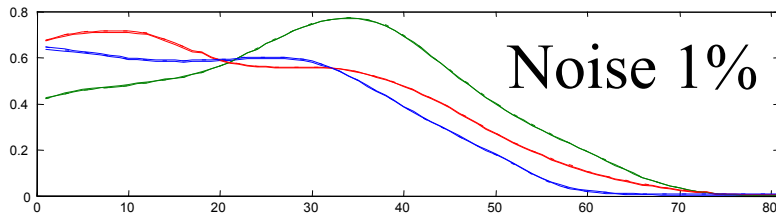
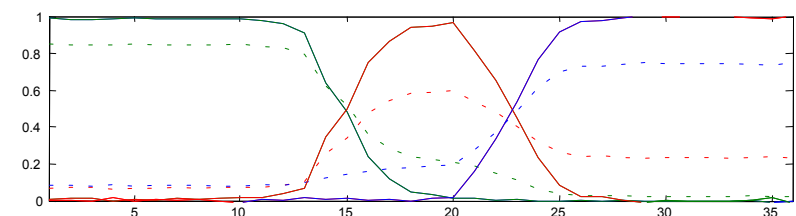
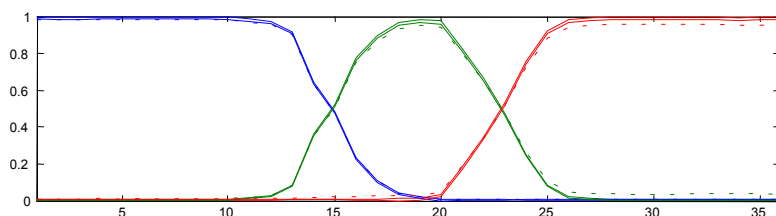
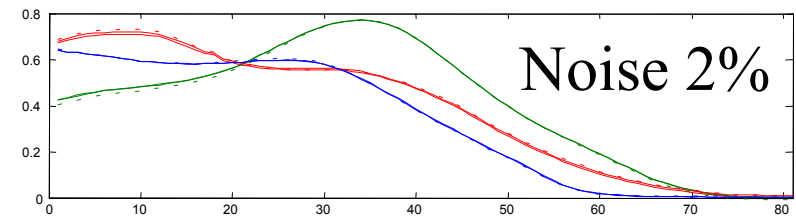
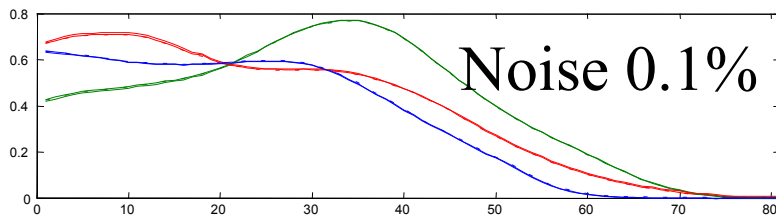
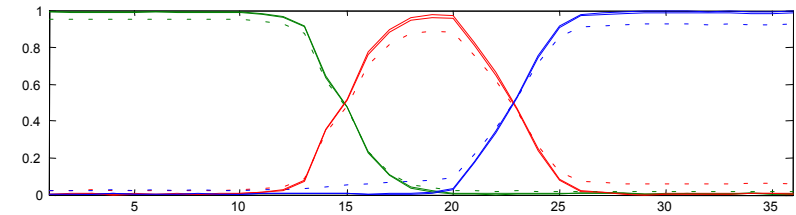
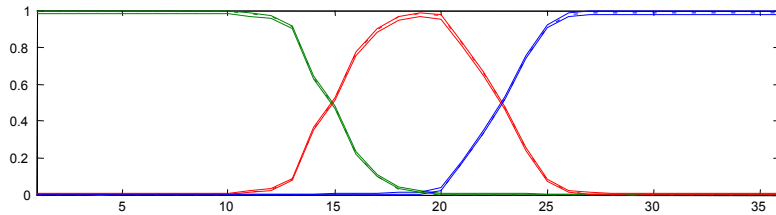
pK_a error estimations

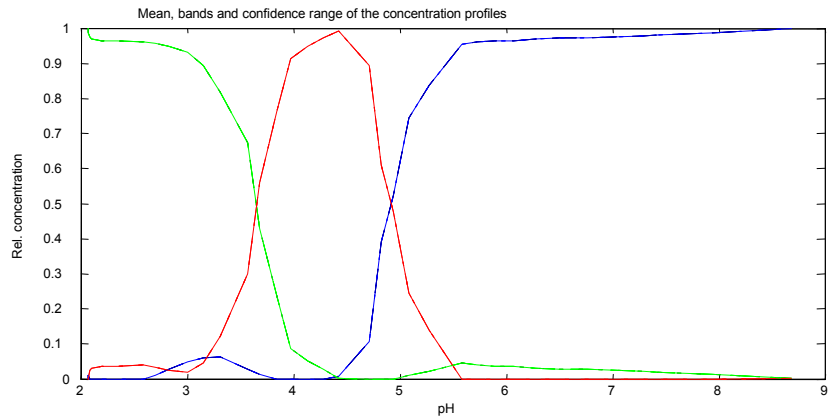
Noise added	pK ₁		pK ₂	
	Value	Std. dev	Value	Std. dev
0 %	3.6660	4e-15	4.9244	9e-15
0.1 %	3.6662	6e-4	4.9243	0.0012
1 %	3.6696	0.0065	4.9262	0.0128
2 %	3.6761	0.0127	4.9173	0.0245
5 %	3.9762	0.4349	5.0745	0.7595

Calculation of band boundaries from mean species profiles error bands (under non-negativity and closure constraints)



Calculation of band boundaries from mean profile error bands (under non-negativity, closure and selectivity constraints)



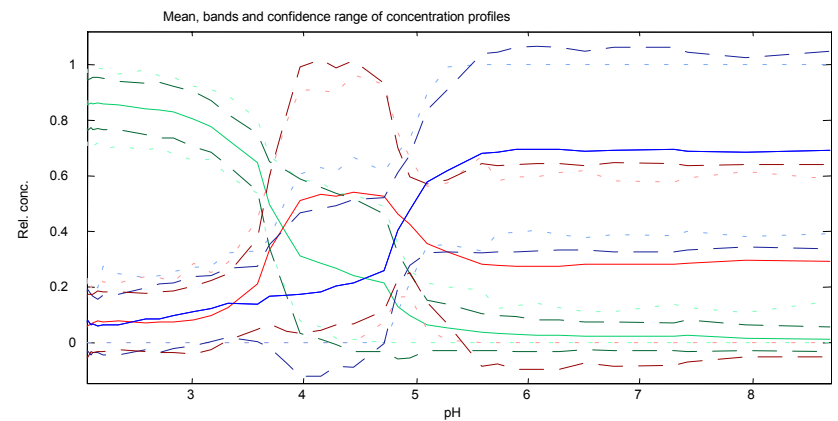
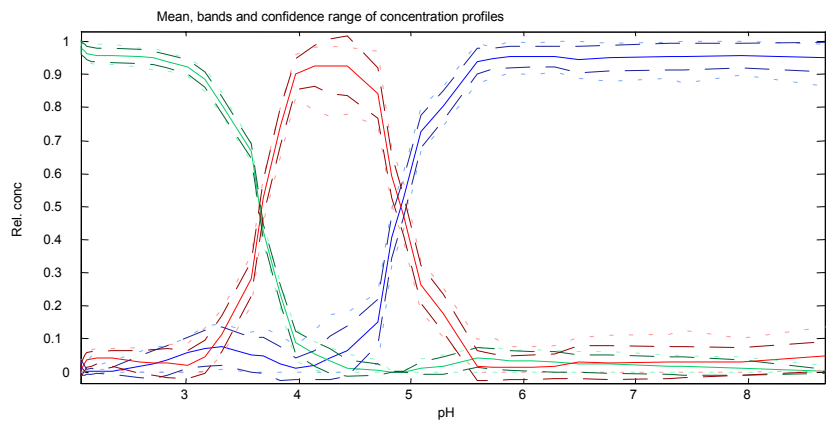
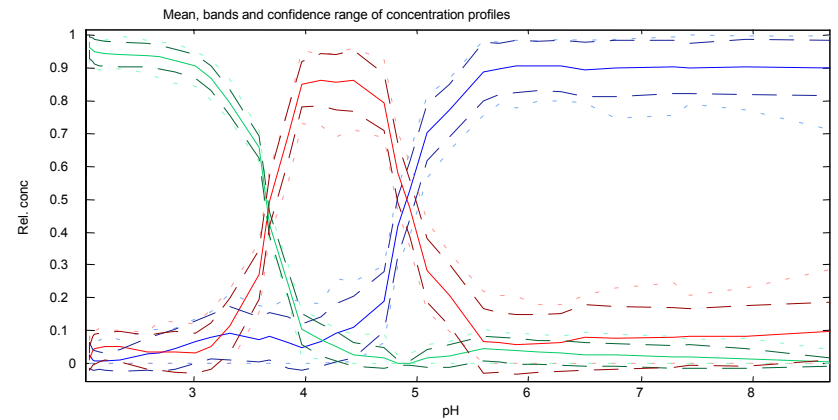
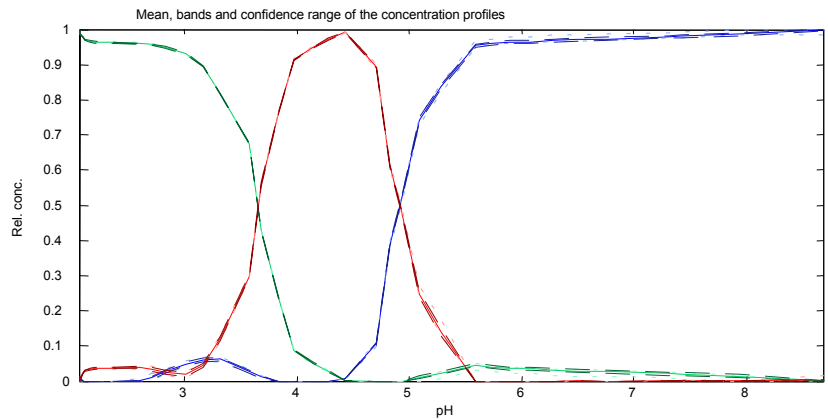


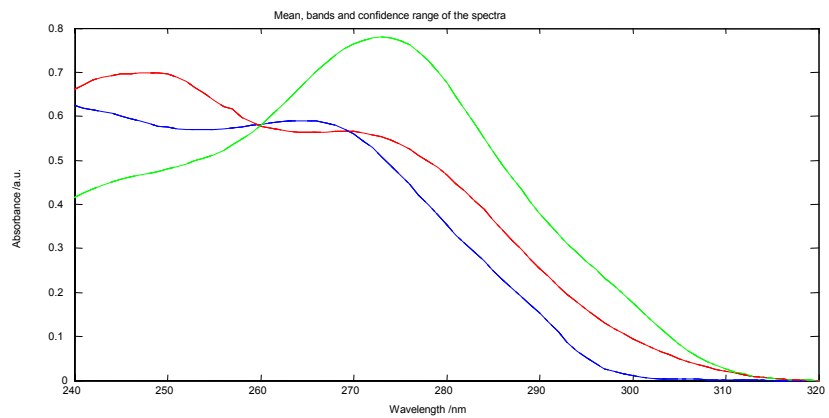
Noise Addition Simulations

Concentration profiles:

Mean max and min profiles

Confidence range profiles



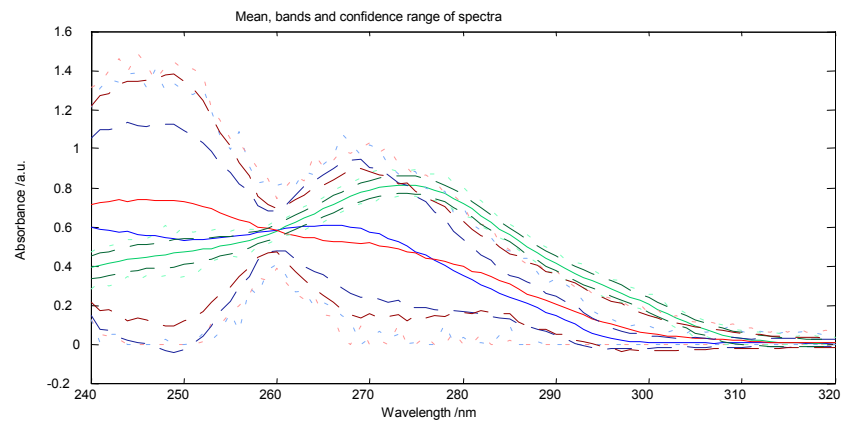
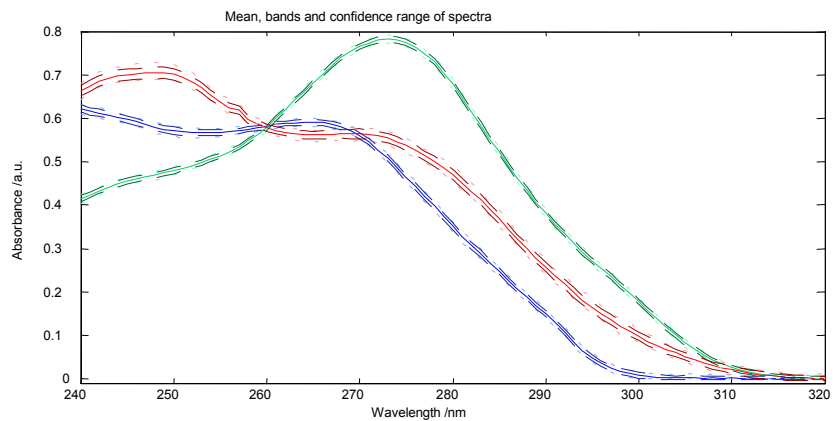
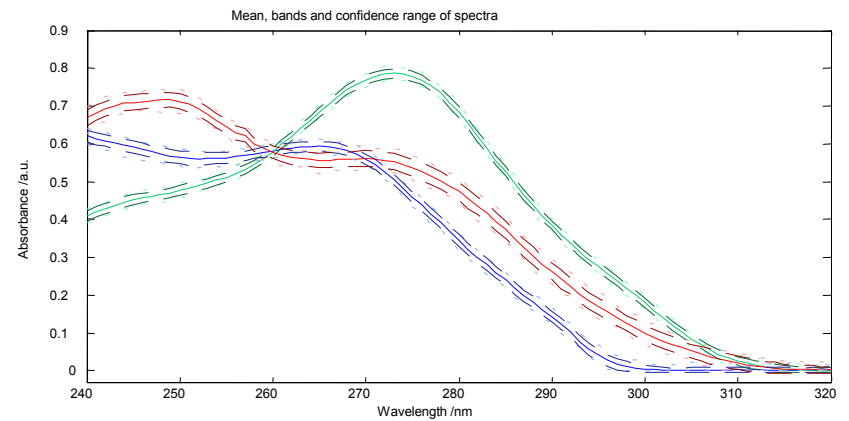
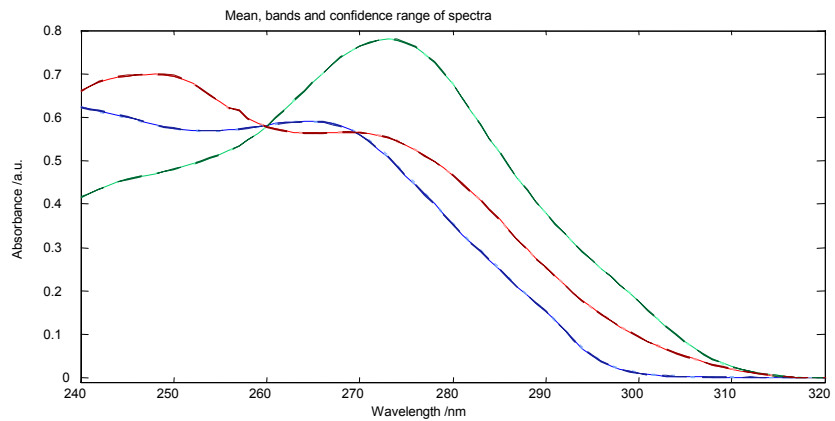


Noise Addition Simulations

Spectra profiles:

Mean, max and min profiles

Confidence range profiles

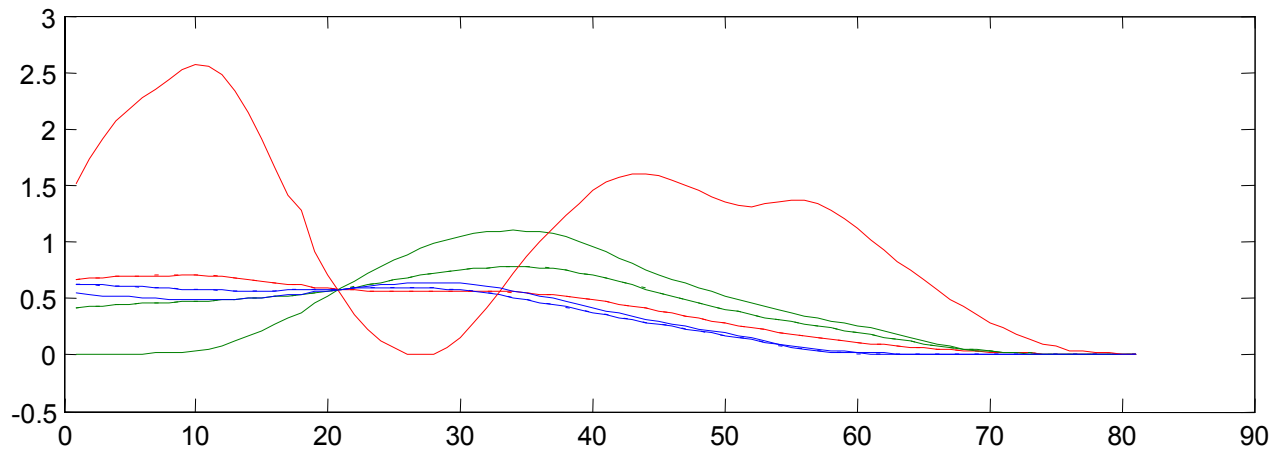
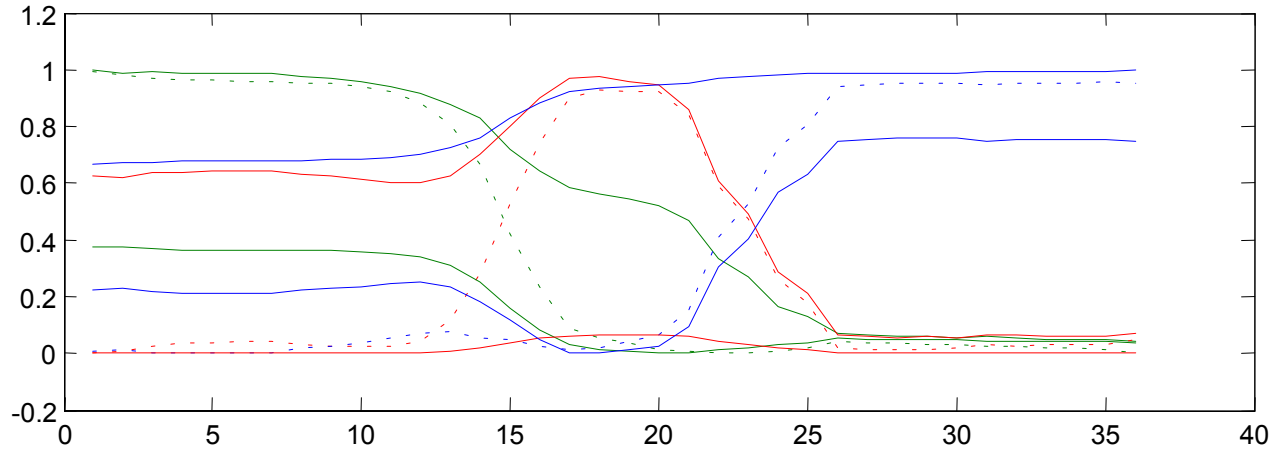


Noise Addition Simulations

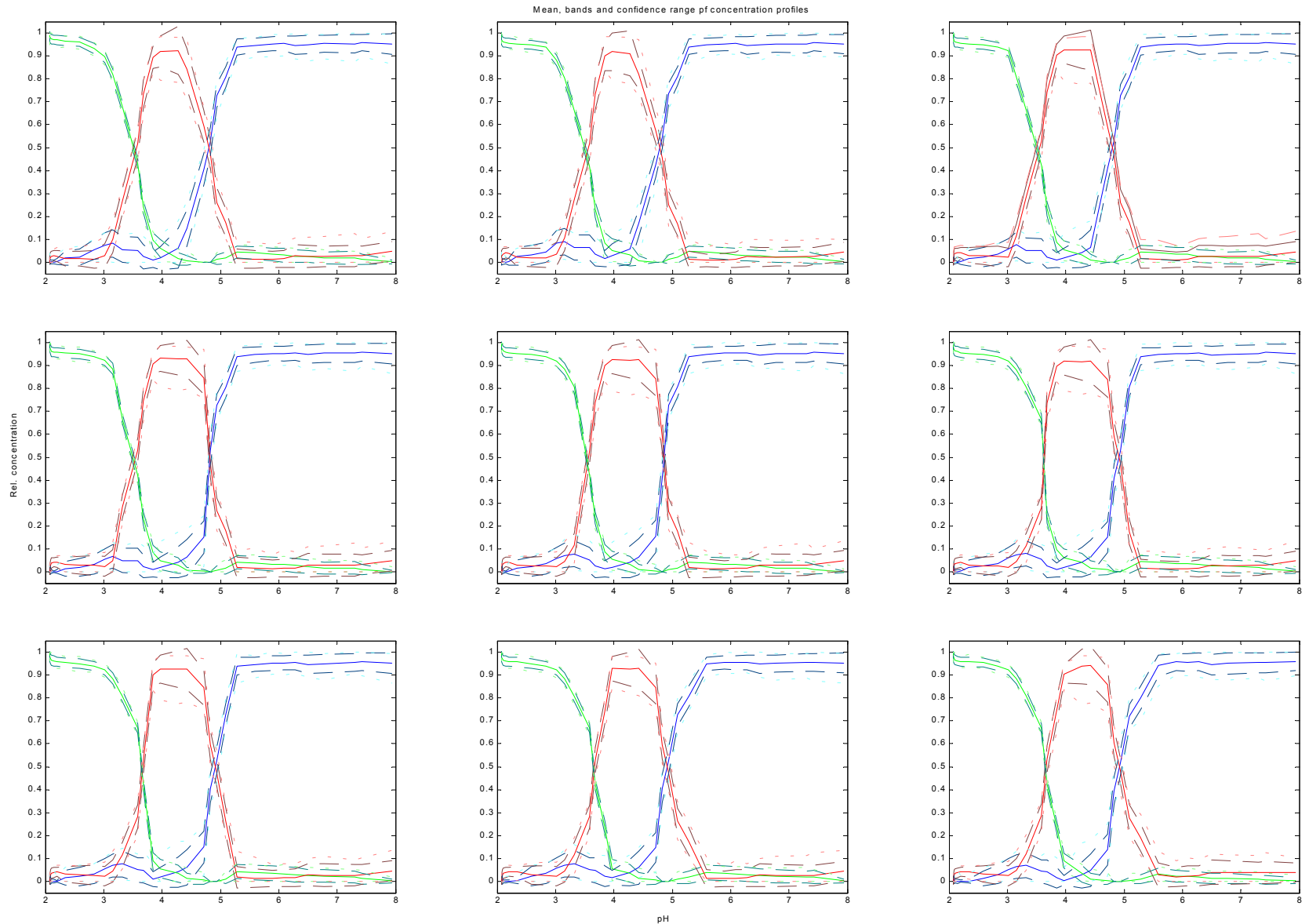
pK_a error estimations

Noise added	pK ₁		pK ₂	
	Value	Std. dev	Value	Std. dev
0 %	3.6539	2e-14	4.9238	2e-14
0.1 %	3.6540	6e-4	4.9226	0.0022
1 %	3.6592	0.0061	4.9134	0.0264
2 %	3.6656	0.0101	4.9100	0.0409
5 %	4.0754	0.4873	5.3308	1.1217

Calculation of band boundaries from mean profile error bands (under non-negativity and closure constraints) at 1% error noise addition

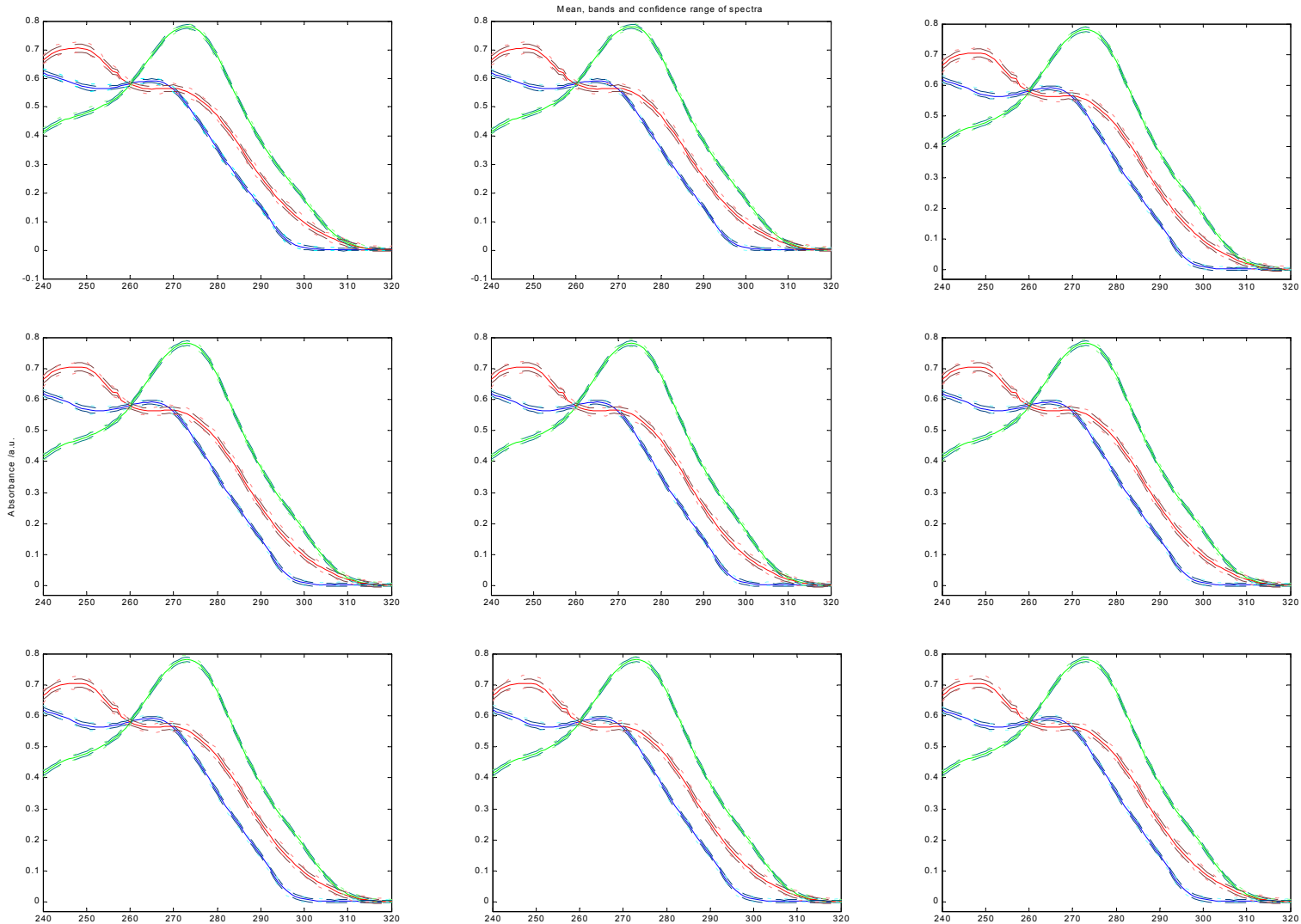


Jackknife Simulations at 1% noise; Concentration profiles: Mean max and min profiles and confidence range profiles



Jackknife Simulations at 1% noise; spectra profiles:

Mean max and min profiles and confidence range profiles



Jackknife Simulations
pKa error estimations
at 1% noise level

N° exp	pK ₁	pK ₂
1	3.6629 ± 0.0066	4.9135 ± 0.0277
2	3.6601 ± 0.0074	4.8989 ± 0.0221
3	3.6590 ± 0.0059	4.9122 ± 0.0261
4	3.6580 ± 0.0056	4.9221 ± 0.0189
5	3.6333 ± 0.0130	4.9018 ± 0.0236
6	3.6882 ± 0.0198	4.9144 ± 0.0267
7	3.6591 ± 0.0064	4.9144 ± 0.0256
8	3.6592 ± 0.0059	4.9144 ± 0.0253
9	3.6582 ± 0.0065	4.9233 ± 0.0239

Parameter Estimation

Summary of results

		Real		0.1 %		1 %		2 %		5 %	
		pk1	pk2	pk1	pk2	pk1	pk2	pk1	pk2	pk1	pk2
Theoretical Value	Value	3.6660	4.9244	-	-	-	-	-	-	-	-
MonteCarlo Simulations	Value	-	-	3.6662	4.9244	3.6696	4.9262	3.6761	4.9173	3.9762	5.0745
	Stand. dev.	-	-	0.0006	0.0012	0.0065	0.0128	0.0127	0.0245	0.4349	0.7595
Noise Addition	Value	-	-	3.6540	4.9226	3.6592	4.9134	3.6656	4.9100	4.0754	5.3308
	Stand. dev.	-	-	0.0006	0.0022	0.0061	0.0264	0.0101	0.0409	0.4873	1.1217
JackKnife	Value	-	-	3.6546	4.9199	3.6598	4.9128	3.6673	4.9131	4.0822	5.3292
	Stand. dev.	-	-	0.0038	0.0032	0.0086	0.0244	0.0124	0.0471	0.5145	1.0906

Outline:

- Introduction
- Rotational ambiguities and feasible bands
- Error propagation and resampling methods
- Experimental system and simulations
- Results
- Conclusions

Summary

- Different approaches for calculation of error propagation and prediction intervals of estimations have been compared including: **Monte Carlo simulations**, **Noise addition** resampling approaches and **Jackknife** based methods.
- The obtained results allowed a preliminary investigation of the **noise effects on MCR-ALS resolved profiles** and **on parameters** from them estimated, and allowed also a preliminary investigation of noise effects **on rotational ambiguities**.
- The study has been shown for the resolution of a three-component equilibrium system with overlapping concentration and spectra profiles

Conclusions

- Rotational ambiguity effects on species profiles depend on the structure and constraints of the data system.
- Rotational ambiguities effects at low noise levels in a system with low selectivity are more important than error propagation effects
- However, at high noise levels ($\geq 5\%$), error propagation effects became larger than rotational ambiguities effects and they are both mixed and undistinguishable
- Obviously the best is to have a system with enough selectivity (low rotational ambiguities) and with low noise levels (low error propagation)

Poster presentations of the Chemometrics group from the University of Barcelona at CAC2002

ELUCIDATION OF THE STRUCTURE OF A **PROTEIN FOLDING INTERMEDIATE** (MOLTEN GLOBULE STATE) USING MULTIVARIATE CURVE RESOLUTION ALTERNATING LEAST SQUARES (MCR-ALS)

Susana Navea, Anna de Juan and Romà Tauler

MULTIVARIATE CURVE RESOLUTION ALTERNATING LEAST SQUARES ANALYSIS OF THE **CONFORMATIONAL EQUILIBRIA OF THE OLIGONUCLEOTIDE d<TGCTCGCT>**

Joaquim Jaumot, Núria Escaja, Raimundo Gargallo, Enrique Pedroso and Romà Tauler

HARD AND SOFT MODELLING OF ACID-BASE CHEMICAL
EQUILIBRIA OF **BIOMOLECULES** USING **¹H-NMR**

*Joaquim Jaumot, Montserrat Vives, Raimundo Gargallo and Romà
Tauler*

IDENTIFICATION AND DISTRIBUTION OF **MICROCONTA-
MINANTS SOURCES OF NONIONIC SURFACTANTS**, THEIR
DEGRADATION PRODUCTS AND LINEAR ALKYL BENZENE
SULFONATES IN COASTAL WATERS AND SEDIMENTS IN
SPAIN BY MEANS OF CHEMOMETRIC METHODS

Emma Peré-Trepat, Mira Petrovic, Damià Barceló and Romà Tauler

MULTIWAY DATA ANALYSIS OF **ENVIRONMENTAL
CONTAMINATION SOURCES IN SURFACE NATURAL
WATERS** OF CATALONIA (SPAIN)

*Emma Peré-Trepat, Mónica Flo, Montserrat Muñoz, Manel Vilanova,
Josep Caixach, Antoni Ginebreda, Romà Tauler*